

General marginal deformations in open string field theory

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October 6, 2007

SFT 07 at RIKEN

Analytic Solutions for marginal deformations

bosonic string

Schnabl, hep-th/0701248

Kiermaier, Okawa, Rastelli

and Zwiebach, hep-th/0701249

superstring

general



super

Erler, arXiv: 0704.0930

Okawa, arXiv: 0704.0936

Okawa, arXiv: 0704.3612

(The Seitaro Nakamura Prize)

general

Kiermaier & Okawa

arXiv: 0707.4472

(Fuchs, Kroyter & Potting)
arXiv: 0708.2222

super

Kiermaier & Okawa

arXiv: 0708.3394

(Fuchs & Kroyter
arXiv: 0706.0717)

Background independence



The equation of motion of the spacetime theory



Conformal invariance of the world-sheet theory

Open bosonic string field theory

Ground state

tachyonic scalar $T(p)$ in 26 dimensions

First-excited state

massless vector field $A_\mu(p)$

:

Degrees of freedom of string field theory

$\{ T(p), A_\mu(p), \dots \}$

\downarrow
 $S [T(p), A_\mu(p), \dots]$

SU(2) gauge fields A single 2×2 matrix field

$$A_\mu^a(x), a=1,2,3 \rightarrow A_\mu(x) = \frac{1}{2} \sum_{a=1}^3 A_\mu^a(x) \sigma^a$$

$\{ T(p), A_\mu(p), \dots \} \rightarrow$ String field Ξ

= a state in a two-dimensional
conformal field theory

$$\Xi = \int \frac{d^{26}p}{(2\pi)^{26}} \left[\frac{1}{\sqrt{\alpha}} T(p) c_+(0; p) + \frac{1}{\sqrt{\alpha}} A_\mu(p) \alpha_-^\mu c_+(0; p) + \dots \right]$$

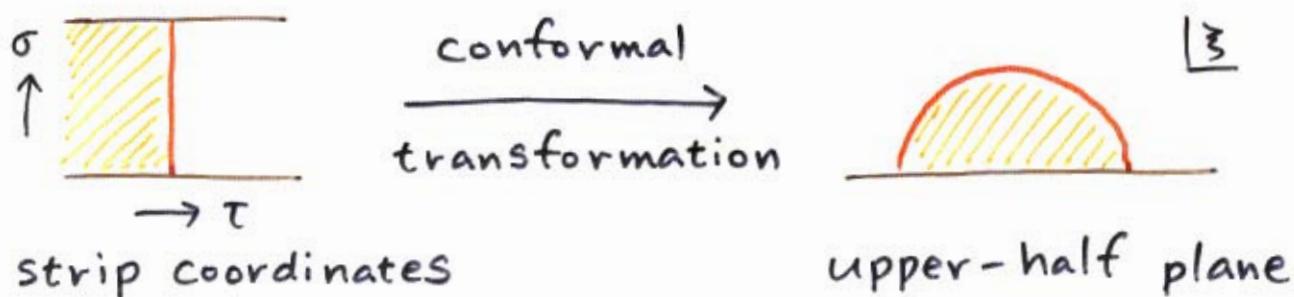
$$A_\mu^a(x) = \text{tr } \sigma^a A_\mu(x)$$

Ξ can be specified by giving $\langle \phi, \Xi \rangle$

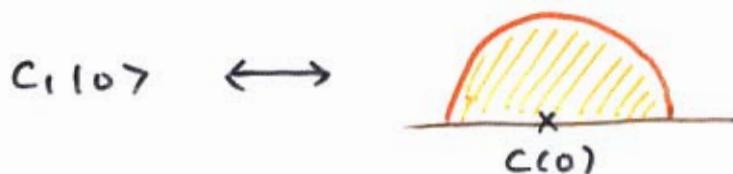
for all ϕ in the Fock space.

CFT description

string field = state in the 2D CFT



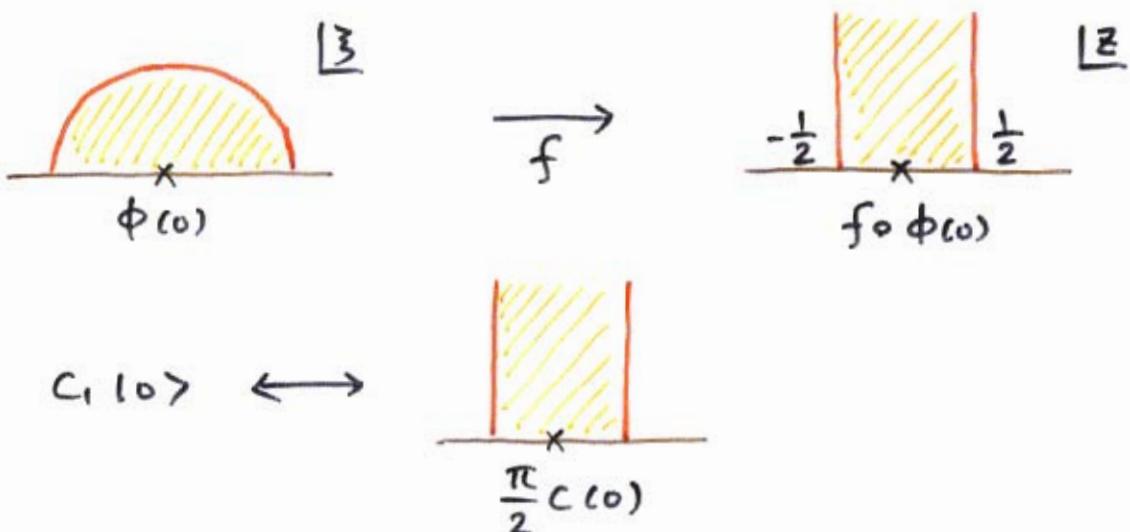
State-operator correspondence



Useful coordinate (sliver frame)

Rastelli & Zwiebach, hep-th/0006240

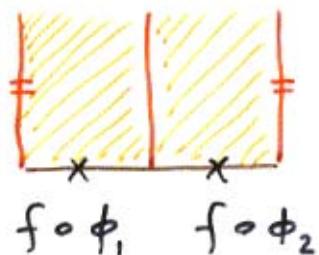
$$z = f(\bar{z}) = \frac{2}{\pi} \arctan \bar{z}$$



$$\left[\begin{array}{l} f \circ c(\bar{z}) = \left(\frac{df(\bar{z})}{d\bar{z}} \right)^{-1} c(f(\bar{z})) \\ f \circ c(0) = \frac{\pi}{2} c(0) \end{array} \right]$$

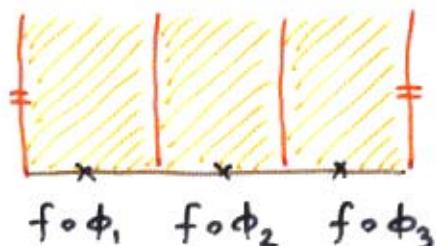
BPZ inner product

$$\langle \phi_1, \phi_2 \rangle =$$



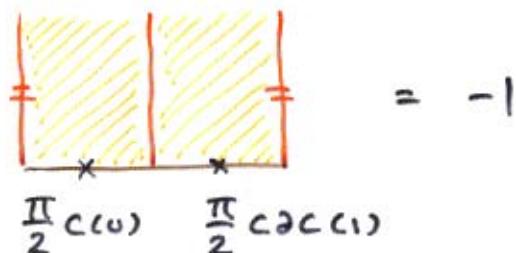
Star product

$$\langle \phi_1, \phi_2 * \phi_3 \rangle =$$

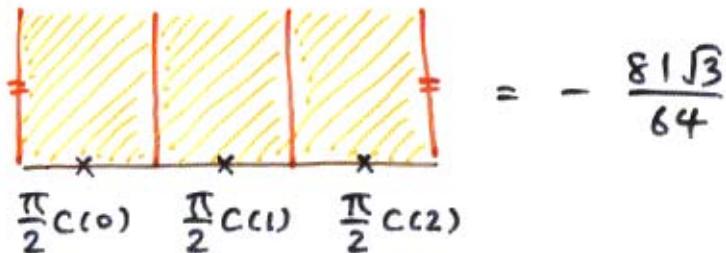


Examples $T = c_{1,10}$

$$\langle T, Q_B T \rangle =$$



$$\langle T, T * T \rangle =$$



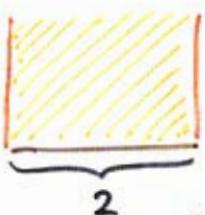
$$\left[\langle c(z_1) c(z_2) c(z_3) \rangle \text{ on } \right]$$



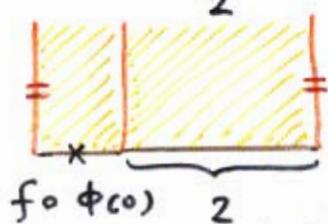
$$= \left(\frac{n}{\pi} \right)^3 \sin \frac{\pi(z_1 - z_2)}{n} \sin \frac{\pi(z_1 - z_3)}{n} \sin \frac{\pi(z_2 - z_3)}{n}$$

Wedge state W_α

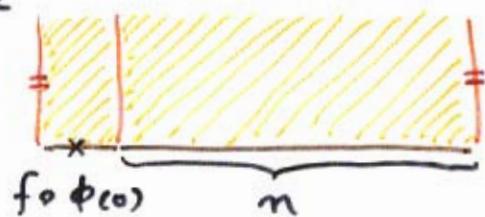
$$|0*0\rangle \longleftrightarrow$$



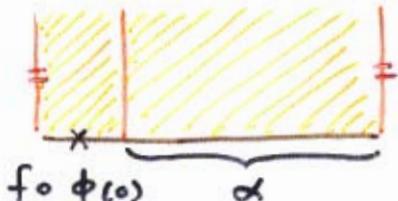
$$\langle \phi, 0*0 \rangle =$$



$$\langle \phi, \underbrace{0*0*0*...*0}_m \rangle =$$



$$\langle \phi, W_\alpha \rangle =$$

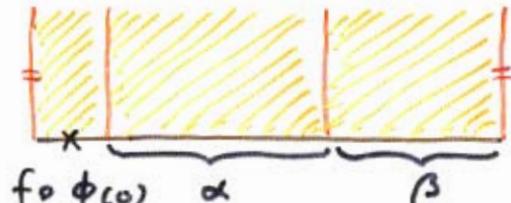


$$W_1 = |0\rangle$$

$$W_2 = |0*0\rangle$$

(α : real)

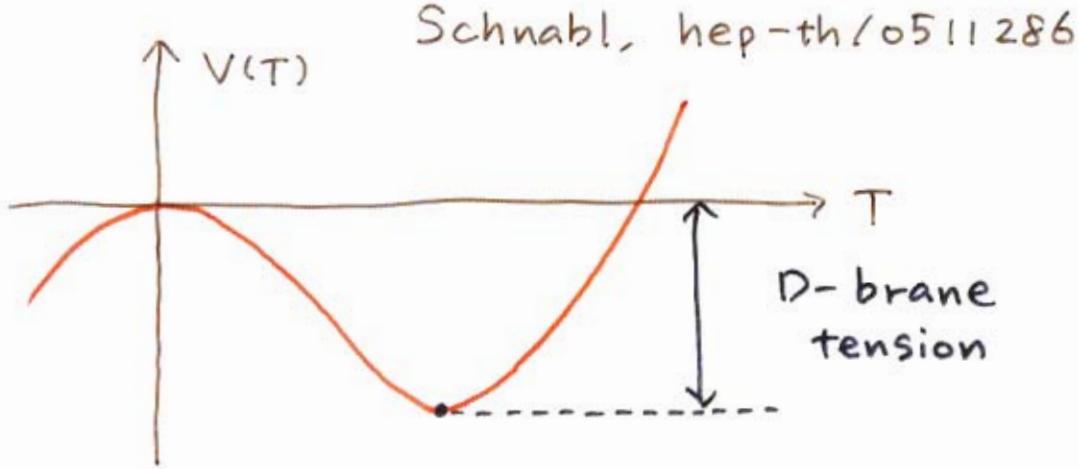
$$\langle \phi, W_\alpha * W_\beta \rangle =$$



$$= \langle \phi, W_{\alpha+\beta} \rangle$$

$$W_\alpha * W_\beta = W_{\alpha+\beta}$$

Schnabl's analytic solution for tachyon condensation

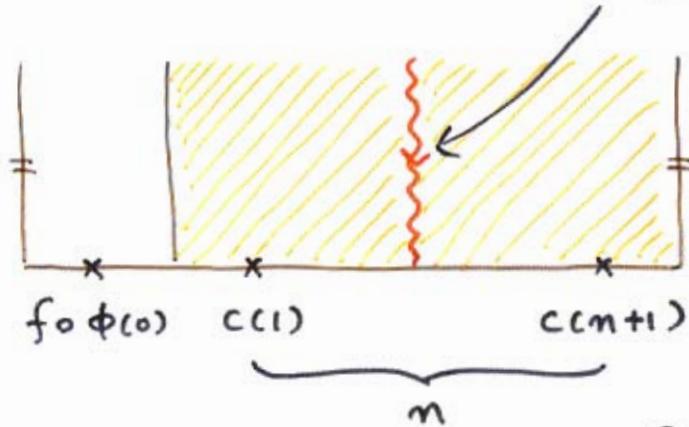


$$\mathcal{I} = \lim_{N \rightarrow \infty} \left[\sum_{n=0}^N \psi'_n - \psi_N \right]$$

$$\psi'_n = \frac{d}{dn} \psi_n$$

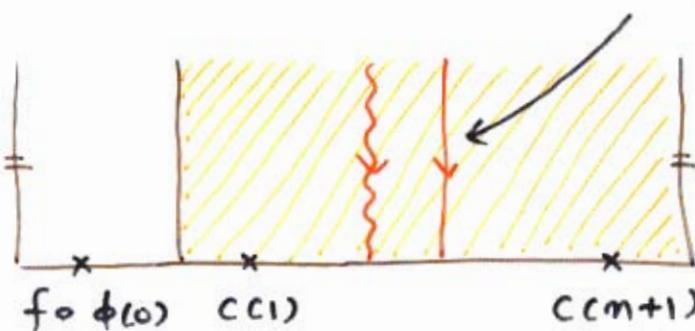
$$B = \int \frac{dz}{2\pi i} b(z)$$

$$\langle \phi, \psi_n \rangle =$$



$$L = \int \frac{dz}{2\pi i} T(z)$$

$$\langle \phi, \psi'_n \rangle =$$



$$[B, L] = 0$$

$$(\text{cf. } L_0 e^{-t L_0} = - \partial_t e^{-t L_0})$$

Marginal deformations

The deformation of the boundary CFT

$$S \rightarrow S + \lambda \int dt V(t)$$

is marginal if V is a primary field of dimension one.

Examples

$$- V(z) = i \sqrt{\frac{2}{\alpha'}} \partial X^M(z)$$

constant mode of the gauge field
or transverse coordinate of the D-brane

$$- V(t) = : \cos \frac{X(t)}{\sqrt{\alpha'}} :$$

$$\text{---} \longrightarrow \dots \quad \text{D25-brane} \qquad \text{D24-branes}$$

For any dimension-one matter primary field V ,
 cV is BRST closed.

$$\mathbb{I}^{(1)} = \begin{array}{c} \text{---} \\ | \\ | \\ \times \\ cV \end{array} \Rightarrow Q_B \mathbb{I}^{(1)} = 0$$

When the deformation is exactly marginal,
we expect a solution of the form

$$\underline{\Psi} = \sum_{n=1}^{\infty} \lambda^n \underline{\Psi}^{(n)} \quad \lambda : \text{deformation parameter}$$

to the nonlinear equation of motion:

$$Q_B \underline{\Psi} + \underline{\Psi} * \underline{\Psi} = 0.$$

$$Q_B \underline{\Psi}^{(1)} = 0$$

$$Q_B \underline{\Psi}^{(2)} = - \underline{\Psi}^{(1)} * \underline{\Psi}^{(1)}$$

:

$$Q_B \underline{\Psi}^{(n)} = - \sum_{m=1}^{n-1} \underline{\Psi}^{(m)} * \underline{\Psi}^{(n-m)}$$

Formally,

$$\underline{\Psi}^{(n)} = - \frac{b_0}{L_0} [\underline{\Psi}^{(1)} * \underline{\Psi}^{(1)}]$$

$$b_0 = \oint \frac{d\beta}{2\pi i} \oint b(\beta), \quad L_0 = \oint \frac{d\beta}{2\pi i} \oint T(\beta)$$

Marginal deformations
with regular operator products

$V(t_1) V(t_2) \cdots V(t_n)$: regular

Schnabl, hep-th/0701248 ; KORZ, hep-th/0701249

$$\begin{aligned}\bar{\Psi}^{(2)} &= - \frac{B}{L} [\bar{\Psi}^{(1)} * \bar{\Psi}^{(1)}] \\ &= - \int_0^\infty dT B e^{-TL} [\bar{\Psi}^{(1)} * \bar{\Psi}^{(1)}]\end{aligned}$$

Subtle where

$$\begin{aligned}(\text{Later}) \quad B &= \oint \frac{dz}{2\pi i} z b(z) = \oint \frac{d\beta}{2\pi i} \frac{f(\beta)}{f'(\beta)} b(\beta) \\ &= b_0 + \frac{2}{3} b_2 - \frac{2}{15} b_4 + \dots \\ L &= \{ Q_B, B \}\end{aligned}$$

$$\boxed{\bar{\Psi}^{(2)} = \int_0^1 dt \quad \left[\begin{array}{c} \text{cV} \quad \text{cV} \\ \hline x \quad x \\ \hline \frac{1}{2} \quad t \quad \frac{1}{2} \end{array} \right]}$$

$$\begin{aligned}
 Q_B \bar{\Psi}^{(2)} &= - \int_0^1 dt \left[\begin{array}{c|c} cV & \\ \hline x & x \end{array} \right] = - \int_0^1 dt \frac{\partial}{\partial t} \left[\begin{array}{c|c} cV & cV \\ \hline x & x \end{array} \right] \\
 &= - \left[\begin{array}{c|c} cV & cV \\ \hline x & x \end{array} \right]_{t=1} + \left[\begin{array}{c|c} cV & cV \\ \hline x & x \end{array} \right]_{t \rightarrow 0} \\
 &\quad \text{-- } \bar{\Psi}^{(1)} * \bar{\Psi}^{(1)}
 \end{aligned}$$

$$\lim_{\epsilon \rightarrow 0} cV(0) cV(\epsilon) = 0 \Rightarrow Q_B \bar{\Psi}^{(2)} = - \bar{\Psi}^{(1)} * \bar{\Psi}^{(1)}$$

If $\lim_{\epsilon \rightarrow 0} V(0) V(\epsilon) = \text{finite or vanishing}$,

$\bar{\Psi}^{(2)}$ is finite and $Q_B \bar{\Psi}^{(2)} = - \bar{\Psi}^{(1)} * \bar{\Psi}^{(1)}$.

$$\bar{\Xi}^{(n)} = \int d^{n-1}t$$

where $\int d^{n-1}t = \int_0^1 dt_1 \int_0^1 dt_2 \cdots \int_0^1 dt_{n-1}$

$$Q_B \bar{\Xi}^{(m)} = - \sum_m \int d^{n-1}t$$

$$= - \sum_m \int d^{n-1}t \frac{\partial}{\partial t_m}$$

$$= - \sum_m \int d^{n-2}t$$

$$= - \sum_m \bar{\Xi}^{(m)} * \bar{\Xi}^{(n-m)}$$

Example

$$V(t) = \exp \left[\frac{1}{\sqrt{\alpha'}} X^\circ(t) \right]$$

rolling tachyon

half S-brane decay

An exact time-dependent solution

incorporating all α' corrections.

In general, $V(t_1) V(t_2) \dots V(t_n)$ are singular.

$$\left(\text{e.g. } V(z) V(w) \sim \frac{1}{(z-w)^2} \right)$$

$\mathbb{E}^{(2)}$ and $\mathbb{E}^{(3)}$ for the singular case were constructed in hep-th/0701249

- regularization
- counterterms

Not all marginal deformations are exactly marginal.

→ obstruction for the construction of $\mathbb{E}^{(2)}$ when the deformation is not exactly marginal at $O(\lambda^2)$.

Generalization to higher orders does not seem so easy.

$\mathbb{E}^{(n)}$
n unintegrated vertex operators
n-1 integrals of moduli
n-1 b-ghost insertions

Integrated vertex operators are more closely related to finite deformations of boundary CFT.

New strategy

$\mathbb{E}^{(n)}$ one unintegrated vertex operator
n-1 integrated vertex operators

General marginal deformations

Kiermaier & Okawa, arXiv: 0707.4472

Unintegrated vertex operator

$$Q_B \cdot cV(t) = 0$$

Integrated vertex operator

$$Q_B \cdot \int_a^b dt V(t) = \int_a^b dt \partial_t [cV(t)] = cV(b) - cV(a)$$

A solution (when the OPE is regular)

$$\Xi_L^{(2)} = \int_1^2 dt \quad \begin{array}{|c|} \hline V(t) \\ \hline \xrightarrow{\quad} \\ \hline cV(t) \\ \hline \end{array}$$

$$\begin{aligned} Q_B \cdot \int_1^2 dt cV(1) V(t) &= - \int_1^2 dt cV(1) \partial_t [cV(t)] \\ &= - cV(1) cV(2) \end{aligned}$$

$$\begin{aligned} \Xi_L^{(3)} & \frac{1}{2} cV(1) \left[\int_1^3 dt V(t) \right]^2 \\ & - \frac{1}{2} cV(1) \left[\int_2^3 dt V(t) \right]^2 \quad \text{on } W_3 \\ \text{or} \quad & \int_1^2 dt_1 \int_{t_1}^3 dt_2 cV(1) V(t_1) V(t_2) \quad \text{on } W_3 \end{aligned}$$

$\bar{\Psi}_L^{(n)}$ ingredients $e^{\lambda V(a,b)}$, $\lambda cV(a) e^{\lambda V(a,b)}$
 where $V(a,b) \equiv \int_a^b dt V(t)$

fixed wedge state W_n

We only need the relations

$$Q_B \cdot e^{\lambda V(a,b)} = e^{\lambda V(a,b)} \lambda cV(b) - \lambda cV(a) e^{\lambda V(a,b)}$$

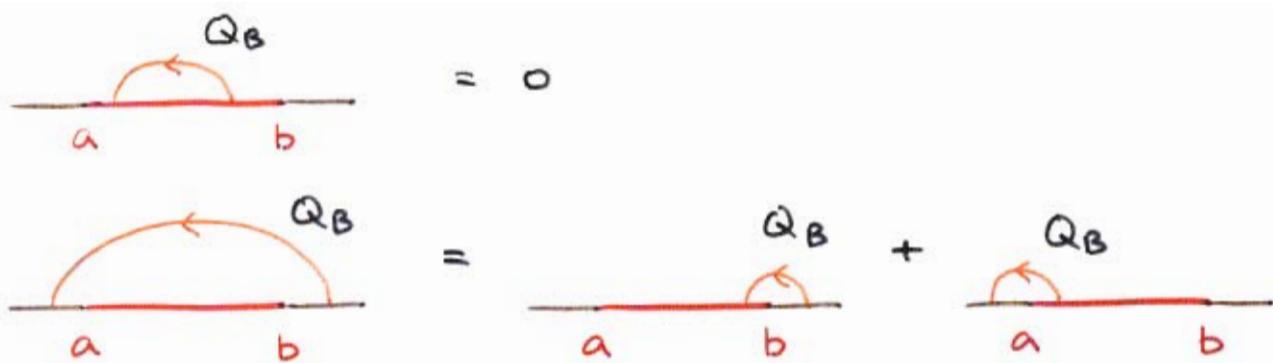
and

$$Q_B \cdot [\lambda cV(a) e^{\lambda V(a,b)}] = -\lambda cV(a) e^{\lambda V(a,b)} \lambda cV(b).$$

These relations generalize
 to the singular case.

$\bar{\Psi}_L$ does not satisfy the reality condition.

$\bar{\Psi}_L \rightarrow$ a real solution by a gauge transformation



Change of boundary conditions

$$e^{\lambda V(a,b)} = 1 + \lambda \int_a^b dt V(t) + \frac{\lambda^2}{2} \int_a^b dt_1 \int_a^{t_1} dt_2 V(t_1) V(t_2) + \dots$$

\downarrow
 $[e^{\lambda V(a,b)}]_r$ singular case
 \curvearrowleft renormalization

$$Q_B \cdot [e^{\lambda V(a,b)}]_r = [e^{\lambda V(a,b)} O_{R(b)}]_r - [O_L(a) e^{\lambda V(a,b)}]_r$$



$$Q_B \cdot [O_L(a) e^{\lambda V(a,b)}]_r = - [O_L(a) e^{\lambda V(a,b)} O_{R(b)}]_r$$

$$O_L = \lambda cV + O(\lambda^2), \quad O_R = \lambda cV + O(\lambda^2)$$

Assumptions

$$\frac{\lambda_1}{a_1} \quad \frac{\lambda_2}{a_2} \quad \frac{\lambda_3}{a_3} \quad \frac{\lambda_4}{a_4} \quad \frac{\lambda_5}{a_5} \quad \left[\prod_{i=1}^n e^{\lambda_i V(a_i, a_{i+1})} \right]_r \quad a_i < a_{i+1}$$

$$(I) Q_B \cdot [e^{\lambda V(a, b)}]_r = [e^{\lambda V(a, b)} O_R(b)]_r - [O_L(a) e^{\lambda V(a, b)}]_r$$

$$(II) Q_B \cdot [O_L(a) e^{\lambda V(a, b)}]_r = - [O_L(a) e^{\lambda V(a, b)} O_R(b)]_r$$

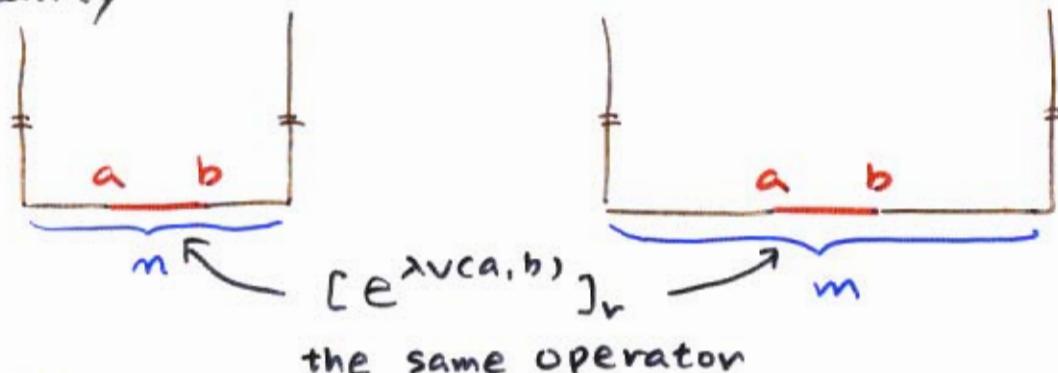
(III) Replacement

$$[\dots e^{\lambda_i V(a_i, a_{i+1})} e^{\lambda_i V(a_{i+1}, a_{i+2})} \dots]_r \\ = [\dots e^{\lambda_i V(a_i, a_{i+2})} \dots]_r$$

(IV) Factorization

$$[\dots e^{\lambda_{j-1} V(a_{j-1}, a_j)} e^{\lambda_{j+1} V(a_{j+1}, a_{j+2})} \dots]_r \\ = [\dots e^{\lambda_{j-1} V(a_{j-1}, a_j)}]_r [\dots e^{\lambda_{j+1} V(a_{j+1}, a_{j+2})} \dots]_r$$

(V) Locality



(VI) Reflection

$$\left[\exp \left(\lambda \int_a^b dt V(a+b-t) \right) \right]_r = \left[\exp \left(\lambda \int_a^b dt V(t) \right) \right]_r$$

[(III), (IV), and (V) with O_L and/or O_R as well.]

Solutions

$$[e^{\lambda V(a,b)}]_r = \sum_{n=0}^{\infty} \lambda^n [V^{(n)}(a,b)]_r$$

Define U by

$$U = 1 + \sum_{n=1}^{\infty} \lambda^n U^{(n)}$$

$$U^{(n)} : [V^{(n)}(1,n)]_r \text{ on } W_n$$

Assumption (I)

$$\rightarrow Q_B \cdot [V^{(n)}(a,b)]_r$$

$$= \sum_{r=1}^n [V^{(n-r)}(a,b) O_R^{(r)}(b)]_r - \sum_{\ell=1}^n [O_L^{(\ell)}(a) V^{(n-\ell)}(a,b)]_r$$

$$(O_L = \sum_{n=1}^{\infty} \lambda^n O_L^{(n)}, O_R = \sum_{n=1}^{\infty} \lambda^n O_R^{(n)})$$

$$Q_B U = A_R - A_L$$

$$A_L = \sum_{n=1}^{\infty} \lambda^n A_L^{(n)}, \quad A_R = \sum_{n=1}^{\infty} \lambda^n A_R^{(n)}$$

$$A_L^{(n)} : \sum_{\ell=1}^n [O_L^{(\ell)}(1) V^{(n-\ell)}(1,n)]_r \text{ on } W_n$$

$$A_R^{(n)} : \sum_{r=1}^n [V^{(n-r)}(1,n) O_R^{(r)}(n)]_r \text{ on } W_n$$

Define $\bar{\Xi}_L$ and $\bar{\Xi}_R$ by

$$\bar{\Xi}_L = A_L * U^{-1}, \quad \bar{\Xi}_R = U^{-1} * A_R$$

We claim that

$$Q_B \bar{\Xi}_L + \bar{\Xi}_L * \bar{\Xi}_L = 0, \quad Q_B \bar{\Xi}_R + \bar{\Xi}_R * \bar{\Xi}_R = 0$$

$\Xi_L \rightarrow \Xi_R$ by a gauge transformation

$$\Xi_R = U^{-1} * \Xi_L * U + U^{-1} * Q_B U$$

Real solution

$$\Xi_{\text{real}} = \frac{1}{\sqrt{U}} * \Xi_L * \sqrt{U} + \frac{1}{\sqrt{U}} * Q_B \sqrt{U}$$

U^{-1} , \sqrt{U} , and $\frac{1}{\sqrt{U}}$ are well defined perturbatively because $U = 1 + O(\lambda)$.

The construction of solutions is divided into two steps

Step 1 (boundary CFT)

Construction of $[e^{\lambda V(a,b)}]_r$.

Step 2 (string field theory)

$[e^{\lambda V(a,b)}]_r \rightarrow \Xi_L, \Xi_R, \Xi_{\text{real}}$

We have explicitly constructed $[e^{\lambda V(a,b)}]_r$ for a class of marginal deformations which include

$$V(t) = \frac{i}{\sqrt{2}\alpha'} \partial_t X^M(t), \sqrt{2} : \cos \frac{X^M(t)}{\sqrt{2}\alpha'} : , \sqrt{2} : \cosh \frac{X^0(t)}{\sqrt{2}\alpha'} :$$

$$\begin{aligned} Q_B \Xi_L &= Q_B (A_L * U^{-1}) \\ &= Q_B A_L * U^{-1} + A_L * U^{-1} * Q_B U * U^{-1} \\ &= Q_B A_L * U^{-1} + A_L * U^{-1} * (A_R - A_L) * U^{-1} \\ &= (Q_B A_L + A_L * U^{-1} * A_R) * U^{-1} - \Xi_L * \Xi_L \end{aligned}$$

$$- Q_B A_L = A_L * U^{-1} * A_R$$



$$Q_B \Xi_L + \Xi_L * \Xi_L = 0$$

Generalization of wedge states

Define U_α ($\alpha \geq 0$) by

$$U_\alpha = \sum_{n=0}^{\infty} \lambda^n U_\alpha^{(n)} \quad U_\alpha^{(n)}: [V^{(n)}_{1, n+\alpha}]_r \text{ on } W_{n+\alpha}$$

$$U_0 = U$$

$$U_\alpha = W_\alpha + O(\lambda)$$

$$\text{Assumptions (III), (IV), and (V)} \rightarrow U_{\alpha+\beta} = U_\alpha * U^{-1} * U_\beta$$

If we introduce $A * B = A * U^{-1} * B$,

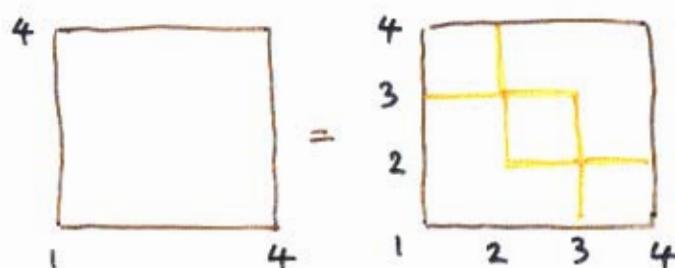
$$U_{\alpha+\beta} = U_\alpha * U_\beta$$

$$\text{Example: } U_2 = U_1 * U^{-1} * U_1 \text{ at } O(\lambda^2)$$

$$U_2^{(2)} = U_1^{(0)} * U_1^{(2)} + U_1^{(1)} * U_1^{(1)} + U_1^{(2)} * U_1^{(0)} - U_1^{(0)} * U_1^{(2)} * U_1^{(0)}$$

$$[V(1,4)^2]_r$$

$$= [V(2,4)^2]_r + 2[V(1,2)]_r [V(3,4)]_r + [V(1,3)^2]_r \quad \begin{matrix} \nearrow \\ - [V(2,3)^2]_r \end{matrix}$$



$$1 < 2 < 3 < 4$$

$$\text{on } W_4$$

Outline of the proof

$$- Q_B A_L \sim \sum_{l,r} [U_{l+r} \text{ with } \lambda^l O_L^{(l)} \text{ and } \lambda^r O_R^{(r)}]$$

$$A_L * U^{-1} * A_R \sim \sum_l [U_l \text{ with } \lambda^l O_L^{(l)}] * U^{-1} * \sum_r [U_r \text{ with } \lambda^r O_R^{(r)}]$$

$$\sim \sum_{l,r} [U_l * U^{-1} * U_r \text{ with } \lambda^l O_L^{(l)} \text{ and } \lambda^r O_R^{(r)}]$$

$$U_{l+r}$$

$$\Rightarrow -Q_B A_L = A_L * U^{-1} * A_R$$

String field theory around the deformed background

$$S = -\frac{1}{g^2} \left[\frac{1}{2} \langle \bar{\Psi}, Q_B \bar{\Psi} \rangle + \frac{1}{3} \langle \bar{\Psi}, \bar{\Psi} * \bar{\Psi} \rangle \right]$$

$$\bar{\Psi} = \bar{\Psi}_0 + \delta \bar{\Psi} \quad \bar{\Psi}_0: \text{a solution}$$

$$S = S_0 - \frac{1}{g^2} \left[\frac{1}{2} \langle \delta \bar{\Psi}, \tilde{Q}_B \delta \bar{\Psi} \rangle + \frac{1}{3} \langle \delta \bar{\Psi}, \delta \bar{\Psi} * \delta \bar{\Psi} \rangle \right]$$

$$\text{where } \tilde{Q}_B A = Q_B A + \bar{\Psi}_0 * A - (-1)^A A * \bar{\Psi}_0.$$

We find that

$$S = S_0 - \frac{1}{g^2} \left[\frac{1}{2} \langle \langle \bar{\Psi}, Q_B \bar{\Psi} \rangle \rangle + \frac{1}{3} \langle \langle \bar{\Psi}, \bar{\Psi} * \bar{\Psi} \rangle \rangle \right]$$

where

$$A * B \equiv A * U^{-1} * B$$

$$Q_A \equiv Q_B A + A_L * A - (-1)^A A * A_R$$

$$\langle \langle A, B \rangle \rangle \equiv \langle A, U^{-1} * B * U^{-1} \rangle$$

$$\bar{\Psi} = \bar{\Psi}_{\text{real}} + \frac{1}{\sqrt{U}} * \bar{\Psi} * \frac{1}{\sqrt{U}}$$

Open superstring field theory

Berkovits, hep-th/9503099

The world-sheet SCFT

$$\left\{ \begin{array}{l} c=15 \text{ matter SCFT} \\ bc \text{ ghosts} \\ \beta\gamma \text{ ghosts} \rightarrow \eta, \bar{\eta}, \phi \quad (\gamma \approx \eta e^\phi, \beta \approx 2\bar{\eta} e^{-\phi}) \end{array} \right.$$

Unintegrated vertex operator in the -1 picture

$ce^{-\phi} \hat{V}_{1/2}$ $\hat{V}_{1/2}$: a superconformal primary field
of dimension $1/2$

$$Q_B \cdot ce^{-\phi} \hat{V}_{1/2}(z) = 0$$

Include β_0 and $\eta_0 \rightarrow$ the large Hilbert space

The equation of motion of the free theory

$$Q_B \eta_0 \stackrel{?}{=} 0$$

Gauge transformations

$$\delta \stackrel{?}{=} Q_B \Lambda + \eta_0 \Omega$$

Grassmann even

$$\stackrel{?}{=} \Phi^{(1)}$$



$$V = c \beta e^{-\phi} \hat{V}_{1/2}$$

The equation of motion of the interacting theory

$$\eta_0 (e^{-\phi} Q_B e^{\phi}) \stackrel{?}{=} 0$$

WZW-like $\partial z \leftrightarrow Q_B, \partial \bar{z} \leftrightarrow \eta_0$

(All string products are defined using the star product.)

Marginal deformations

$$S \rightarrow S + \lambda \int dt V_1(t)$$

$$\text{where } V_1 = G_{-1/2} \cdot \hat{V}_{1/2}$$

$$\stackrel{?}{=} \lambda \stackrel{?}{=} + O(\lambda^2)$$

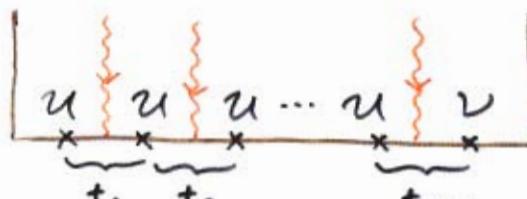
Marginal deformations for the superstring with regular operator products

Analytic solutions Erler, arXiv: 0704.0930
 Okawa, arXiv: 0704.0936

$$\Phi = -\ln(1-H)$$

where

$$H = \sum_{n=1}^{\infty} \lambda^n \int d^{n-1}t$$



$$u \equiv Q_B \cdot v$$

Erler's idea

Replace cv in the bosonic solution by $Q_B \cdot v$

$$\begin{aligned} \Phi &= \lambda Q_B \Phi'' + O(\lambda^2) \\ Q_B \Phi + \Phi^2 &= 0 \end{aligned} \quad \left. \right\} \rightarrow \text{pure gauge}$$

$$\eta_0 \Phi = 0$$

Solutions to $e^{-\Phi} Q_B e^\Phi = \Phi$

also solve the equation of motion.

Real Solutions

① Find a real solution to

$$Q_B G + [\Phi, G] = \frac{d}{d\lambda} \Phi$$

$$\Rightarrow e^{\Phi_{\text{real}}} = P \exp \left[\int_0^\lambda d\lambda' G(\lambda') \right]$$

Okawa, arXiv: 0704.3612

$$② e^{\Phi_{\text{real}}} = \frac{1}{\sqrt{e^\Phi (e^\Phi)^*}} e^\Phi \quad (Q_B [e^\Phi (e^\Phi)^*] = 0)$$

Erler, arXiv: 0704.0930 v2

General marginal deformations for the superstring

Kiermaier & Okawa, arXiv: 0708.3394

Integrated vertex operator in the 0 picture

$$V(a, b) = \int_a^b dt V_1(t) = \int_a^b dt G_{-1/2} \cdot \hat{V}_{1/2}(t)$$

$$Q_B \cdot V(a, b) = [c V_1(b) + \eta e^\phi \hat{V}_{1/2}(b)] - [c V_1(a) + \eta e^\phi \hat{V}_{1/2}(a)]$$

Any BRST-closed state is BRST exact
in the large Hilbert space because

$$\exists R(t) \text{ such that } Q_B \cdot R(t) = 1$$

$$\text{we choose } R(t) = -c \bar{z} \partial \bar{z} e^{-2\phi}(t)$$

$$\lim_{\epsilon \rightarrow 0} R(t-\epsilon) [c V_1(t) + \eta e^\phi \hat{V}_{1/2}(t)] = c \bar{z} e^{-\phi} \hat{V}_{1/2}(t)$$

↑
solution to the linearized
equation of motion

$$Q_B \cdot [e^{\lambda V(a, b)}]_r = [e^{\lambda V(a, b)} O_R(b)]_r - [O_L(a) e^{\lambda V(a, b)}]_r$$

as in the bosonic case.

Ingredients: $[e^{\lambda V(a, b)}]_r$, $[O_L(a) e^{\lambda V(a, b)}]_r$,
 $[e^{\lambda V(a, b)} O_R(b)]_r$, and $R(t)$

Solutions

Define U , A_L , A_R , Ξ_L , and Ξ_R as before.

Define \hat{A}_L and \hat{A}_R by

$$\hat{A}_L = \sum_{n=1}^{\infty} \lambda^n \hat{A}_L^{(n)}, \quad \hat{A}_R = \sum_{n=1}^{\infty} \lambda^n \hat{A}_R^{(n)}$$

$$\hat{A}_L^{(n)}: \lim_{\epsilon \rightarrow 0} \sum_{r=1}^n R(1-\epsilon) [O_L^{(r)}(1), V^{(n-r)}(1, n)]_r \text{ on } W_n$$

$$\hat{A}_R^{(n)}: - \lim_{\epsilon \rightarrow 0} \sum_{r=1}^n [V^{(n-r)}(1, n) O_R^{(r)}(n)]_r R(n+\epsilon) \text{ on } W_n$$

$$Q_B A_L = - A_L U^{-1} A_R \rightarrow Q_B \hat{A}_L = A_L + \hat{A}_L U^{-1} A_R$$

Define Ξ_L and Ξ_R by

$$e^{\Xi_L} = 1 + \hat{A}_L U^{-1}, \quad e^{-\Xi_R} = 1 - U^{-1} \hat{A}_R$$

$$\begin{aligned} Q_B e^{\Xi_L} &= (A_L + \hat{A}_L U^{-1} A_R) U^{-1} - \hat{A}_L U^{-1} (A_R - A_L) U^{-1} \\ &= (1 + \hat{A}_L U^{-1}) A_L U^{-1} \\ &= e^{\Xi_L} \Xi_L \end{aligned}$$

$$\eta_0(e^{-\Xi_L} Q_B e^{\Xi_L}) = \eta_0 \Xi_L = 0$$

$$\text{Similarly, } \eta_0(e^{-\Xi_R} Q_B e^{\Xi_R}) = 0$$

Real solution

$$e^{\Xi_{\text{real}}} = \frac{1}{\sqrt{e^{\Xi_L} U e^{-\Xi_R}}} e^{\Xi_L \sqrt{U}}$$

$$(Q_B (e^{\Xi_L} U e^{-\Xi_R})) = 0, \quad \eta_0 U = 0)$$

Conclusions and discussion

We have constructed analytic solutions for any exactly marginal deformation in any boundary (S)CFT when $[e^{\lambda V(a,b)}]_r$ is given.

New characterization of exact marginality using the BRST formalism

(cf. Recknagel & Schomerus, hep-th/9811237)

Study explicit solutions.

- rolling tachyons
- lower-dimensional D-branes

Backgrounds not connected by marginal deformations

Background independence

The equation of motion of the spacetime theory
 \longleftrightarrow Conformal invariance of the world-sheet theory

Our new solutions have little relevance to Schnabl's tachyon vacuum solution.
— Let's see how far we can get!